

An Alternating Augmented Lagrangian method for constrained nonconvex optimization

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Introduction

Problem Statement

$$\begin{array}{ll} \min_x & f(x) \\ \text{s.t.} & x \in X \cap Y, \end{array}$$

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a continuously differentiable function,
- X, Y are nonempty, convex, closed sets, “easy to treat separately”.

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$$\begin{array}{ll} \min_x & f(x) \\ \text{s.t.} & a^T x = b, \\ & l \leq x \leq u. \end{array}$$

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ADMM (DRS)

Reformulation

$$\begin{aligned} \min_{x,y} \quad & f(x) \\ \text{s.t.} \quad & x \in X, y \in Y, \\ & x - y = 0. \end{aligned}$$

ADMM

$$\begin{aligned} x^{k+1} &\in \operatorname{argmin}_{x \in X} f(x) + \lambda^k T(x - y^k) + \frac{\tau}{2} \|x - y^k\|^2, \\ y^{k+1} &= \operatorname{argmin}_{y \in Y} \lambda^k T(x^{k+1} - y) + \frac{\tau}{2} \|x^{k+1} - y\|^2, \\ \lambda^{k+1} &= \lambda^k + \tau(x^{k+1} - y^{k+1}). \end{aligned}$$

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Convergence of ADMM

- convergence is well understood in the convex case,
- the non convex case is an open research topic,
- τ is a “fixed” parameter,
- τ is a critical parameter for the performances of ADMM.

τ in practice

$$\tau_{k+1} = \begin{cases} \alpha_1 \tau_k & \text{if } \|x^{k+1} - y^{k+1}\| > \mu \|y^{k+1} - y^k\|, \\ \tau_k / \alpha_2 & \text{if } \|y^{k+1} - y^k\| > \mu \|x^{k+1} - y^{k+1}\|, \\ \tau_k & \text{otherwise.} \end{cases}$$

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An Augmented Lagrangian approach

Augmented Lagrangian framework

Solve (approximately) a sequence of subproblems of the form

$$\min_{x \in X, y \in Y} q_{\tau^k, \lambda^k}(x, y) \triangleq L_{\tau^k}(x, y, \lambda^k) = f(x) + \lambda^{kT}(x - y) + \frac{\tau^k}{2} \|x - y\|^2,$$

with

- increasing τ^k ,
- bounded λ^k .

The framework (ALF)

$$\alpha > 1, \sigma \in (0, 1), \tau_0 > 0,$$

$$\{\epsilon_k\} \text{ s.t. } \lim_{k \rightarrow \infty} \epsilon_k = 0, \Lambda \leftarrow \text{bounded set};$$

for $k=0, 1, 2 \dots$ **do**

$$(x^{k+1}, y^{k+1}) \leftarrow \epsilon_k\text{-stationary point for } \min_{x \in X, y \in Y} q_{\tau_k, \lambda^k}(x, y);$$

$$\lambda^{k+1} \leftarrow \lambda^k + \tau_k(x^{k+1} - y^{k+1});$$

$$\lambda^{k+1} \leftarrow [\lambda^{k+1}]_{\Lambda}^+;$$

if $\|x^{k+1} - y^{k+1}\| \leq \sigma \|x^k - y^k\|$ **then**

$$| \tau_{k+1} = \tau_k;$$

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$$| \tau_{k+1} = \alpha \tau_k;$$

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Convergence

Theorem

Let $\{(x^k, y^k)\}$ be the sequence generated by Algorithm ALF. Then every cluster point (\bar{x}, \bar{y}) of $\{(x^k, y^k)\}$ is such that $\bar{x} = \bar{y}$ and \bar{x} is a critical point of the original problem i.e.

$$\|\bar{x} - [\bar{x} - \nabla f(\bar{x})]_{X \cap Y}^+\| = 0.$$

Towards ADMM

Roadmap

- design a solver for the subproblems that employ the ADMM steps,
- change the `argmin` operation to something suitable for the non convex setting,
- embed it in the ALF.

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Alternate Minimization (AM)

Let $x^0 \in X, y^0 \in Y,$

$t = 0;$

while (x^t, y^t) is not an ϵ -stationary point **do**

find x^{t+1} such that $q_{\tau, \lambda}(x^{t+1}, y^t) \leq q_{\tau, \lambda}(x^t, y^t)$ and

$$\nabla_x q_{\tau, \lambda}(x^{t+1}, y^t)^T (x - x^{t+1}) \geq 0 \quad \forall x \in X;$$

find y^{t+1} such that

$$y^{t+1} \in \operatorname{argmin}_{y \in Y} q_{\tau, \lambda}(x^{t+1}, y);$$

$t = t + 1;$

end

- checking $\nabla_x q_{\tau, \lambda}(x^{t+1}, y^t)^T (x - x^{t+1}) \geq 0 \quad \forall x \in X$ may be difficult in practice.

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Alternate Minimization v2

Let $x^0 \in X$, $y^0 \in Y$,

$t = 0$;

while (x^t, y^t) is not an ϵ -stationary point **do**

 find x^{t+1} such that

$$q_{\tau, \lambda}(x^{t+1}, y^t) \leq q_{\tau, \lambda}(x^t + \alpha_t d^t, y^t),$$

 where $d^t = [x^t - \nabla_x q_{\tau, \lambda}(x^t, y^t)]_X^+ - x^t$ and α_t is obtained with an Armijo-type line search;

$y^{t+1} = \operatorname{argmin}_{y \in Y} q_{\tau, \lambda}(x^{t+1}, y)$;

$t = t + 1$;

end

Convergence of AM

Proposition

Algorithm AM(v2) determines in a finite number of iterations a point $(x(\epsilon), y(\epsilon))$ which is an ϵ -stationary point for problem

$$\min_{x \in X, y \in Y} L_{\tau}(x, y, \lambda).$$

The complete algorithm (ALTALM)

$\alpha > 1$, $\sigma \in (0, 1)$, $\tau_0 > 0$, $\{\epsilon_k\}$ s.t. $\lim_{k \rightarrow +\infty} \epsilon_k = 0$, $\Lambda \leftarrow$ bounded set;

for $k=0, 1, 2 \dots$ **do**

$x^t, y^t \leftarrow x^k, y^k$;

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Numerical Experiments

SVM training - Indefinite Kernels

$$\min_x f(x) \triangleq \frac{1}{2} x^T Q x - e^T x$$

$$\text{s.t. } a^T x = 0,$$

$$0 \leq x_i \leq C \quad \forall i \in 1, \dots, n.$$

$$Q_{ij} \triangleq a_i a_j K(u_i, u_j),$$

u_i are the patterns of the dataset,

a_i are the labels.

- The *sigmoid kernel*:

$$K(u, v) = \tanh(a u^T v + b),$$

- The *gaussian combination kernel*:

$$k(u, v) = \exp\left(-\frac{\|u - v\|^2}{\sigma_1}\right) + \exp\left(-\frac{\|u - v\|^2}{\sigma_2}\right) - \exp\left(-\frac{\|u - v\|^2}{\sigma_3}\right).$$

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The augmented Lagrangian subproblem

$$\begin{aligned} \min_{x,y} \quad & \frac{1}{2}x^T Qx - e^T x + \lambda^T(x - y) + \frac{\tau}{2}\|x - y\|^2 \\ \text{s.t.} \quad & 0 \leq x_i \leq C \quad \forall i \in 1, \dots, n \\ & a^T y = 0. \end{aligned}$$

- QP solver for the x step,
- closed form solution for y

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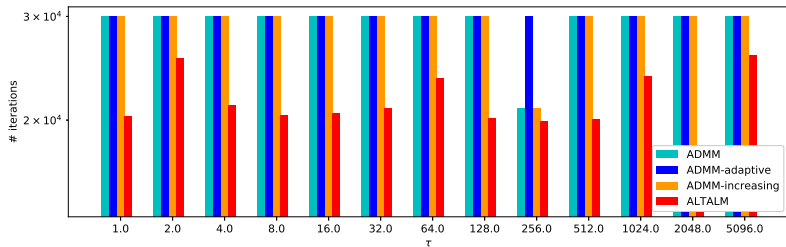
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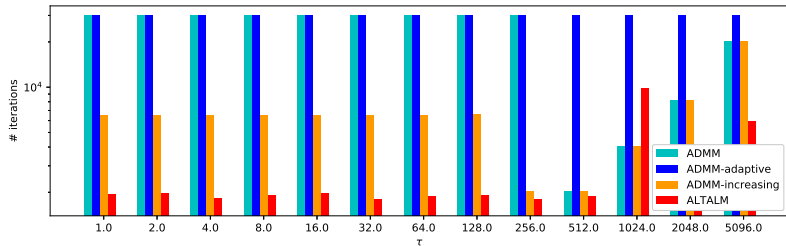
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UCI liver-disorder dataset (345 examples, 7 attributes)



(a) Sigmoidal kernel.



(b) Gaussian mixture kernel.

Wrap up

- “same” 3 fundamental steps,
- different convergence proofs,
- ALTALM naturally deals with the non convex setting,
- different assumptions on and role of τ ,
- ALTALM has a double loop (weakness?),
- ALTALM compares favorably in the numerical experiments.

Thank you!